

MLFB-Ordering data

6SL3220-1YE26-0AF0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Item no. :
Consignment no. :
Project :

Rated data			General tech. specifications	
Input			Power factor λ	0.70 0.85
Number of phases	3 AC		Offset factor cos φ	0.96
Line voltage	380 480 V +10 % -20 %		Efficiency η	0.98
Line frequency	47 63 Hz		Sound pressure level (1m)	67 dB
Rated voltage	400V IEC	480V NEC	Power loss	0.316 kW
Rated current (LO)	24.50 A	24.50 A	Filter class (integrated)	RFI suppression filter for Category C2
Rated current (HO)	16.96 A	18.25 A		
Output			Ambient conditions	
Number of phases	3 AC		Standard board coating type	Class 3C2, according to IEC 60721-3
Rated voltage	400V IEC	480V NEC	Standard board coating type	3: 2002
Rated power (LO)	11.00 kW	15.00 hp	Cooling	Air cooling using an integrated fan
Rated power (HO)	7.50 kW	10.00 hp		
Rated current (LO)	26.00 A	21.00 A	Cooling air requirement	0.018 m ³ /s (0.653 ft ³ /s)
Rated current (HO)	18.00 A	14.00 A	Installation altitude	1000 m (3280.84 ft)
Rated current (IN)	27.00 A		Ambient temperature	
Max. output current	35.00 A		Operation	-20 45 °C (-4 113 °F)
Pulse frequency	4 kHz		Transport	-40 70 °C (-40 158 °F)
Output frequency for vector control	0 200 Hz		Storage	-25 55 °C (-13 131 °F)
			Relative humidity	
Output frequency for V/f control	0 550 Hz		Max. operation	95 % At 40 °C (104 °F), condensatio and icing not permissible

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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Figure simila

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Mechanical data		Closed-loop control techniques	
Degree of protection	IP20 / UL open type V/f linear / square-law / parameter FSC		rizable Yes
Net weight	8 kg (16.89 lb)	V/f with flux current control (FCC)	Yes
	-	V/f ECO linear / square-law	Yes
Width	140 mm (5.51 in)	Sensorless vector control	Yes
Height	295 mm (11.61 in)	Vector control, with sensor	No
Depth	209 mm (8.23 in)	Encoderless torque control	Yes
Inputs / outputs		Encoderiess torque control	. 03
Standard digital inputs		Torque control, with encoder	No
Number	6	Communication	
Switching level: 0→1	11 V		
Switching level: 1→0	5 V	Communication	PROFINET, EtherNet/IP
Max. inrush current	15 mA	Connections	
Fail-safe digital inputs		Signal cable	
Number	1	Conductor cross-section	0.15 1.50 mm ² (AWG 24 AWG 16)
Digital outputs		Line side	
Number as relay changeover contact	2	Version	screw-type terminal
Output (resistive load)	DC 30 V, 5.0 A	Conductor cross-section	1.50 16.00 mm ² (AWG 16 AWG 6)
Number as transistor	0	Motor end	
Analog / digital inputs		Version	Screw-type terminals
Number	2 (Differential input)	Conductor cross-section	1.50 16.00 mm ² (AWG 16 AWG 6)
Resolution	10 bit	DC link (for braking resistor)	
Switching threshold as digital input		PE connection	On housing with M4 screw
0→1	4 V	Max. motor cable length	3
1→0	1.6 V	Shielded	150 m (492.13 ft)
Analog outputs		Unshielded	300 m (984.25 ft)
Number	1 (Non-isolated output)		
PTC/ KTY interface			

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$



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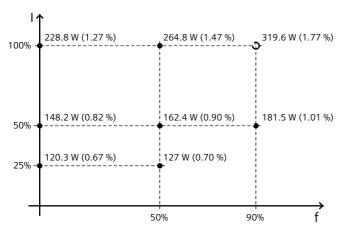
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-34.30 %



 $\label{thm:converter:thm:con$

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Standards

Compliance with standards UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

CE marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

^{*}converted values